

(19) World Intellectual Property
Organization
International Bureau



557517

(43) International Publication Date
9 December 2004 (09.12.2004)

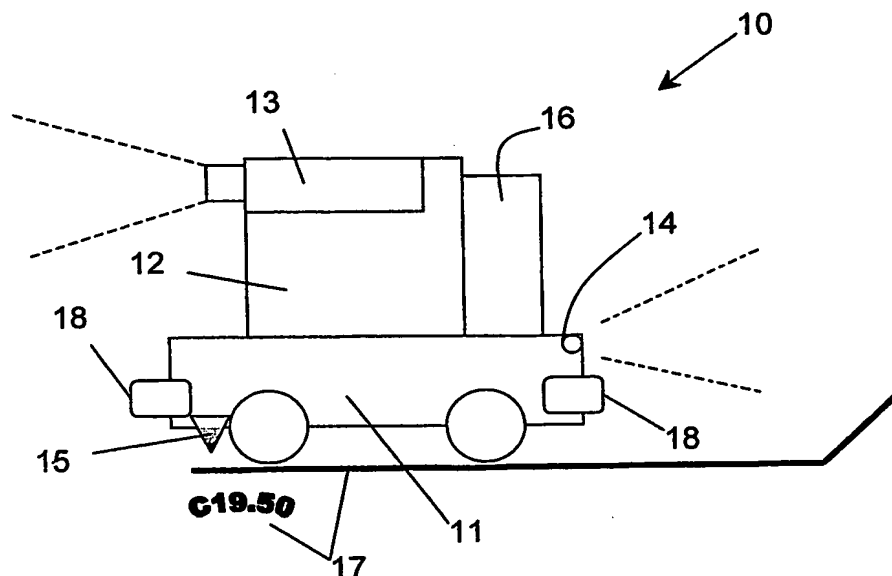
PCT

(10) International Publication Number
WO 2004/107073 A1

- (51) International Patent Classification⁷: **G05D 1/02**, B25J 9/16
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- (21) International Application Number: PCT/SE2004/000811
- (22) International Filing Date: 26 May 2004 (26.05.2004)
- (25) Filing Language: English
- (26) Publication Language: English
- (30) Priority Data: 0301567-4 27 May 2003 (27.05.2003) SE
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- (81) Designated States (unless otherwise indicated, for every kind of national protection available): AE, AG, AL, AM, AT, AU, AZ, BA, BB, BG, BR, BW, BY, BZ, CA, CH, CN, CO, CR, CU, CZ, DE, DK, DM, DZ, EC, EE, EG, ES, FI, GB, GD, GE, GH, GM, HR, HU, ID, IL, IN, IS, JP, KE, KG, KP, KR, KZ, LC, LK, LR, LS, LT, LU, LV, MA, MD, MG, MK, MN, MW, MX, MZ, NA, NI, NO, NZ, OM, PG, PH, PL, PT, RO, RU, SC, SD, SE, SG, SK, SL, SY, TJ, TM, TN, TR, TT, TZ, UA, UG, US, UZ, VC, VN, YU, ZA, ZM, ZW.
- (84) Designated States (unless otherwise indicated, for every kind of regional protection available): ARIPO (BW, GH, GM, KE, LS, MW, MZ, NA, SD, SL, SZ, TZ, UG, ZM, ZW), Eurasian (AM, AZ, BY, KG, KZ, MD, RU, TJ, TM), European (AT, BE, BG, CH, CY, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HU, IE, IT, LU, MC, NL, PL, PT, RO, SE, SI, SK, TR), OAPI (BF, BJ, CF, CG, CI, CM, GA, GN, GQ, GW, ML, MR, NE, SN, TD, TG).

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(54) Title: ROBOT SYSTEM, METHOD AND COMPUTER PROGRAM PRODUCT



(57) Abstract: Robot system including at least one mobile robot (10), for treating a surface, which comprises map storage means to store a map of the surface to be treated and means to navigate the, or each, mobile robot (10) to at least one point on a surface. The, or each, mobile robot (10) comprises locating means (13,14) to identify its position with respect to the surface to be treated and means to automatically deviate the mobile robot (10) away from its initial path in the event that an obstacle is detected along its path. The, or each, mobile robot (10) also comprises means to store and/or communicate data concerning the surface treatment performed and any obstacles detected by the locating means (13,14).

WO 2004/107073 A1



Published:

— *with international search report*

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